# 1 Trie

Motivation for this data structure is to enable fast retrieval of strings and their common prefixes. Operations of interest are: finding, inserting and deleting key.

#### 1.1 Definition

Trie (also known as prefix tree or digital tree) is a tree T defined over alphabet L with the following properties:

- 1. There is one root r(T) only.
- 2. Each node x has arbitrary number of children determined by an array  $d_x[i]$ , where  $i \in L$ . If x is leaf, then  $d_x[i]$  is empty array i.e. it's length  $|d_x|$  is zero.
- 3. For each child  $d_x[i]$  there is character  $c(x) \in L$  from alphabet L which determines prefix for x.
- 4. All leaves and some of internal nodes have associated keys k(x) and corresponding values v(x) determined by characters on the path from root to x. Position of x defines a key associated with it by appending all characters on the path from the root to x.

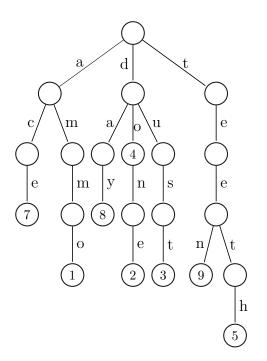


Figure 1: Trie with keys/values: ace/7, ammo/11, day/8, do/4, done/2, dust/3, teen/9, teeth/5

In the pseudo code, root of trie is denoted with root(T). Children of a node x are accessed via  $child(x, i), i \in L$ ; if character i is not present, then the child function returns null. Number of children of x is given with size(x). Value is accessed with value(x). Keys of x's children are taken with  $key(x, i), i \in L$ . Length of a key w is |w|.

#### 1.2 Finding key

The operation checks if the given key K exists in a trie T. It goes one by one character of K until the corresponding child exists. If all characters are traversed, then the key K is found; otherwise, the key does not exist.

Input: string K to check for existence in a trie T Output: key/value pair if exist or null if no such key is present Worst Case Complexity: O(|K|)find(K)  $x = \operatorname{root}(T)$ for i = 1 to |K| chr = K[i]if child(x, chr)  $\neq$  null  $x = \operatorname{child}(x, chr)$ else return null return (key(x), value(x))

#### 1.3 Inserting

The operation puts a key/value pair (K, V) into trie T. It goes one by one character of K and checks whether they exist from the root down to leaves. If a character of K is not found on the path, it is added, as well all remaining characters. If all characters of K exist on the path, then the reached node is updated with value V.

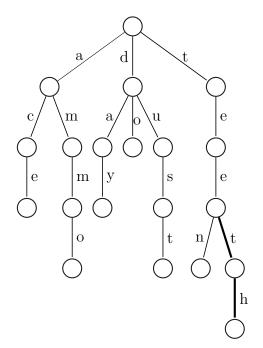


Figure 2: Inserting key *teeth* into trie; bold edges are newly created

Input: key/value (K, V) to insert into trie TOutput: T with (K, V)Worst Case Complexity: O(|K|)insert(K, V)if root(T) = null new root(T)  $p_x = x = root(T)$ for i = 1 to |K| chr = K[i]x = child(x, chr)

```
if x = null
break
p_x = x
while i \le |K|
chr = K[i]
new x
child(p_x, chr) = x
new key(p_x, chr)
p_x = x
value(x) = V
```

#### 1.4 Deleting

Deleting removes a key K from a trie T by traversing path of K and removing nodes which do not have children anymore. It traverses all characters of K from the root down to leaves. Then it goes back by the same path in bottom-up manner to delete nodes without children. When a non-empty node is reached, the deletion is over.

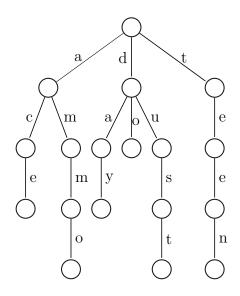


Figure 3: Trie after deleting key teeth.

Input: key K to delete in trie T Output: T without key K and true returned, false if no such key is present Worst Case Complexity: O(|K|)delete(K) if T = nullreturn false {stack of children traversed on the path of the given key} new children node = root(T) for i = 1 to size(K) chr = K[i]if child(node, chr)  $\neq$  null node = child(node, chr) push(children, node) else

```
return false
{go up along the path and delete empty nodes}
i = |K|
chr = K[i]
node = pop(children)
do
  if size(node) \neq 0
    break
  delete node
  {proceed with node parent}
  node = pop(children)
  delete key(node, chr)
  i = i - 1
  if i = 0
    break
  chr = K[i]
```

### 1.5 Worst case complexity

**Theorem 1.1.** For a trie T and a key K, finding, inserting and deleting the key have complexity O(|K|),

**Proof** All operations have loops of size |K|, thus their complexity is O(|K|). QED

## 1.6 Applications

- Associative array.
- Lexicographic sorting.
- Radix sort.

# References

- [1] Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, Clifford Stein: Introduction to Algorithms; Second Edition
- [2] Miodrag Zivkovic: Algoritmi
- [3] Robert Sedgewick: Algorithms
- [4] Daniel Dominic Sleator, Robert Endre Tarjan: Self-Adjusting Binary Search Trees